Software Reliability Models: Failure rate estimation

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Abstract- Software reliability is one of the important factors which decide the quality of the software .Software is thoroughly checked and errors are removed before it is delivered to the client. A key factor in the success of a software project is achieving the best-possible software reliability. Software reliability is a mathematical model which ensures that software development has been done within cost and time and it will not cause failure under specified conditions. Different types of SRMs are used for different phases of the software development life-cycle. In this paper we will compare failure rate of different software reliability models by using SPSS tool. Non-Homogeneous Poisson Processes (NHPPs) are the most commonly used models in the reliability analysis of software.

Index Terms— SRGMs, Software Reliability, NHPP, Failure rate.

I. INTRODUTION

The basic goal of software development is to produce high quality software at low cost and within time. As the size and complexity of the software grows the issues with the reliability of the software also grows. So there is requirement of a software reliability model which ensures that the operation is failure free. It is very desirable to know the probability of software failure or the rate at which software errors will occur. SRGMs are mathematical models which describes how software attains reliability when the faults are detected and removed[1]. It indicates when software is ready to release and it has gain the expected reliability level[7]. Many SRGMs have been proposed in the past to estimate the expected number of total defects (or failures) or the expected number of remaining defects/ failures. Some well known SRGMs are:-

- 1) Goel model (1985)
- 2) Goel and Okumoto model (1979)
- 3) Schick and Wolverton model.
- 4) Musa and Ackerman model (1989)
- 5) Jelinski and Moranda.

Although these models have some limitations. None of the models are good for all data sets[6]; they are ideal for some particular data set but unfit for other data set. In this paper we will consider some SRGMs and estimate the software failure rate of the models by using a common data set for each model and we will use SPSS tool to estimate the failure rate of the SRGMs and compare the results.

II. LITERATURE REVIEW

2.1 Description of Different SRGMs

The SRGMs are used in estimating the reliability metrics of software products. The following assumptions are made for software reliability modelling[3]:-

(i) The fault removal process follows the Non- Homogeneous Poisson process (NHPP)

(ii) The software system is subjected to failure at random time caused by faults remaining in the system.

(iii) The mean time number of faults detected in the time interval $(t, t+\Delta t)$ by the current test effort is proportional for the mean number of remaining faults in the system.

(iv) The proportionality is constant over the time.

(vi) Each time a failure occurs, the fault that caused it is immediately removed and no new faults are introduced.

Let's have a view on some basic parameters before we proceed to details of software reliability models. Let $\{Z(t), t \ge 0\}$ denote a counting process representing the cumulative number of faults detected by the time t. An SRGM based on an NHPP with the mean value function (MVF), m(t) can be formulated as[4]:

$P \{z(t) = n\} = e^{\frac{m(t)!}{2}} \cdot \frac{m(t)!}{n!}$

Where $n = 0, 1, 2, 3, \dots$ And m (t) represents the expected cumulative number of faults detected by the time t. The MVF *m* (t) is non-decreasing with respect to testing time t under the bounded condition $m(\infty) = a$, where a is the expected total number of faults to be eventually detected. Knowing its value can help us to determine whether the software is ready to be released to the customers and how much more testing resources are required[6].

The failure intensity function at testing time t is:-

 λ (t) =d m (t)/dt=m' (t)

The software reliability, i.e., the probability that no failures occur in (s, s+t) given that the last failure occurred at testing time s where $(s \ge 0, t \ge 0)$, is:-

R(t|s) = exp[-m(t+s)-m(t)]

The fault detection rate per fault at testing time t is given by:-

 $d(t)=m'(t)/(a-m(t))=\lambda(t)/(a-m(t))$

In next section, we will discuss the different software reliability models.

2.2 Goel and Okumoto Model.

This model assumes that 1 the number of failure in non overlapping intervals are independent and (2) the expected number of failure is proportional to the expected number of undetected errors. Here, the fault rate with hypothesized mean value function is:-

 $m(\infty) = a^{*}(1 - e^{-i \omega})$

where $m(\infty) =$ expected number of faults detected eventually.

b = fault detection rate.

a = expected total number of faults.

2.3 Jelinski and Moranda Model

This model assumes that:-

1) Failure data take the form of successive independent times between failures.

2) A constant failure rate between failures.

3) A failure rate is proportional to the software's current fault content.

Here, the software failure rate is:-

 $Z(ti) = \Phi[N-(i-1)]$

Where, ti = Time between the $(i-1)^{th}$ and i^{th} failure. N=number of initial errors in the program. Φ =proportionality constant.

2.4 Schick and Wolvertan Model Schick and Wovertan modified the J-M model by considering a time dependent failure intensity function and the time between failures to follow wiebull distribution[2]. Here, the software failure rate is:-

 $\lambda(ti) = \Phi[N-(i-1)]ti$

where, ti = Time between the $(i-1)^{th}$ and i^{th} failure. N=number of initial errors in the program. Φ =proportionality constant.

III. WORKING AND METHODOLOGY

Here we will take a common data set for all the models that consists the time and cumulative faults. And using SPSS tool we will estimate the failure intensity of the models by applying the expressions for failure rate estimation. SPSS tool is IBM's Statistical tool for estimation and calculation. We also find the predicate values for these cumulative faults.

3.1 Goel and Okumoto Model:-

The fault rate with hypothesized mean value function is:-

m (∞) =a*(1-a⁽⁻a⁽)</sup>)

where m (∞) = expected number of faults detected eventually. b = fault detection rate. a = expected total number of faults.

Nonlinear Regression Analysis

Parameter Estimates

			95% Confidence Interval	
Parameter	Estimate	Std. Error	Lower Bound	Upper Bound
А	760.534	139.892	465.388	1055.680
В	.032	.007	.016	.048

Correlations of Parameter

Estimates				
	а	b		
А	1.000	998		
В	998	1.000		

ANOVA ^a					
Source	Sum of Squares	df	Mean Squares		
Regression	953052.512	2	476526.256		
Residual	2656.488	17	156.264		
Uncorrected Total	955709.000	19			
Corrected Total	196108.947	18			

Dependent variable: m^a

a. R squared = 1 - (Residual Sum of Squares) / (Corrected Sum of Squares) = .986.

And we got the predicate value for the data entered

24.15			
47.53			
70.17			
92.09			
113.32			
133.87			
153.77			
173.04			
191.69			
209.76			

3.2 Jelinski and Moranda

the failure intensity decreases in a geometric progression on the occurrence of each individual failure,

 $\lambda i = \lambda K^{i-1}$

Here, the software failure rate is:-

 $Z(ti) = \Phi[N-(i-1)]$

Where, ti = Time between the $(i-1)^{th}$ and ith failure. N=number of initial errors in the program. Φ =proportionality constant.

Parameter Estimates					
			95% Confidence Interval		
Parameter	Estimate	Std. Error	Lower Bound	Upper Bound	
А	-2.240	6641649523364 408.000	- 1407966802015 0300.000	1407966802015 0290.000	
Ν	39.459	3165561226448 77700.000	- 6710690018957 98910.000	6710690018957 99040.000	
Ι	129.735	1236121349756 70992.000	- 2620460199829 73504.000	2620460199829 73792.000	

Correlations of Parameter Estimates

	а	Ν	Ι
А	1.000	925	227
Ν	925	1.000	.580
Ι	227	.580	1.000

ANOVA ^a					
Source	Sum of Squares	df	Mean Squares		
Regression	759600.053	3	253200.018		
Residual	196108.947	16	12256.809		
Uncorrected Total	955709.000	19			
Corrected Total	196108.947	18			

Dependent variable: m^a

a. R squared = 1 - (Residual Sum of Squares) / (Corrected Sum of Squares) = .954

3.3 Schick and Wolvertan Model

Assume the failure rate at the ith time interval increases with time since the last debugging. The program failure rate function between the $(i-1)^{th}$ and the i^{th} failure rate is:-

$$\lambda(t_i) = \phi[N - (i-1)]t_i$$

Parameter Estimates

			95% Confidence Interval	
Parameter	Estimate	Std. Error	Lower Bound	Upper Bound
А	-1.595	9882116.022	-20949151.717	20949148.527
Ν	-76.502	239382896.025	-507469146.327	507468993.324
Ι	-63.208	209622394.459	-444379688.056	444379561.641

Correlations of Parameter Estimates

	а	Ν	Ι
А	1.000	526	237
Ν	526	1.000	.951
Ι	237	.951	1.000

ANOVA ^a					
Source	Sum of Squares	df	Mean Squares		
Regression	949659.362	3	316553.121		
Residual	6049.638	16	378.102		
Uncorrected Total	955709.000	19			
Corrected Total	196108.947	18			

Dependent variable: m^a

a. R squared = 1 - (Residual Sum of Squares) / (Corrected Sum of Squares) = .969.

V. CONCLUSION

After analysing different types of software reliability models and calculating failure rate of the software product we analyzed that the software reliability models ensure the reliability of the software products as the failure rate is nearly 1 for the software models. As much as they are near to 1 they ensure the more reliability of the software product. The work is done using SPSS tool.

VI. FUTURE WORK

The next goal is to optimize the reliability of the soft ware reliability models using genetic algorithms. Genetic programming can help to ensure the reliability of the software product is much better way,

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